

# Spatiotemporal data

ST733 – Spatial Statistics

# Spatiotemporal Data

- ▶ Types of spatiotemporal data:

- ▶ Examples of each type:



## Discrete time, time series models

- ▶ The simplest interesting times series model is the first-order autoregressive (AR1) model:
  
  
  
  
  
  
  
  
  
  
- ▶ The process is stationary :

## Discrete time, time series models

- ▶ The AR1 is equivalent to an exponential spatial correlation model in 1D

## Discrete time, time series models

- ▶ We'll stick with the AR1 case, but this is just a special case of the ARMA( $p, q$ ) model:

## Continuous space, discrete time

- ▶ The spatial AR1 model is:
- ▶ The mean and covariance are:
- ▶ This is an example of separability



# Separability

- ▶ Let  $\mathbf{Y}_t = [Y_t(\mathbf{s}_1), \dots, Y_t(\mathbf{s}_n)]^T$  and  $\mathbf{Y} = (\mathbf{Y}_1^T, \dots, \mathbf{Y}_m^T)$
- ▶  $Y$  is a spatiotemporal GP with mean  $E[Y_t(\mathbf{s})] = \mathbf{X}_t(\mathbf{s})\beta$  and separable covariance:
- ▶ So the joint distribution of  $\mathbf{Y}$  can be written:



# Seperability

- ▶ Facts about the Kronecker product:

# Seperability

- ▶ Using these facts, the likelihood becomes:
  
  
  
  
  
  
  
  
  
  
- ▶ MLE and Bayes are fast if  $n$  and  $m$  are reasonably small
  
  
  
  
  
  
  
  
  
  
- ▶ Prediction, both spatial interpolation (Kriging) and forecasting ahead in time, follows from the conditional normal distributions

# Continuous space, discrete time

- ▶ How to test for separability?

## More flexible models

- ▶ As with stationarity and isotropy, separability is usually unrealistic but leads to huge simplifications
- ▶ Nonseparable models are easy to specify, but hard to fit

## More flexible models

- ▶ Dynamic spatial linear model (DLM):

# Continuous space/continuous time

- ▶  $Y(\mathbf{s}, t)$  is a GP with mean  $\mathbf{X}(\mathbf{s}, t)\beta$  and

$$\text{Cov}[Y(\mathbf{s}, t), Y(\mathbf{s}', t')] = C(\mathbf{s}, \mathbf{s}', t, t')$$

- ▶ Typically we assume separability

$$C(\mathbf{s}, \mathbf{s}', t, t') = C_1(\mathbf{s}, \mathbf{s}')C_2(\mathbf{s}, \mathbf{s}')$$

- ▶ For example,

- ▶ The likelihood is MVN with a Kronecker product for the covariance

## Continuous space/continuous time

- ▶ Is the separable ST covariance valid?
- ▶ We we think of  $(\mathbf{s}, t)$  as a 3D space then any valid GP is 3D is valid
- ▶ Spatiotemporal spectral densities:
  
- ▶ Fact, if the spectral density is separable then the covariance is separable:

# Continuous space/continuous time

- ▶ Non-separable covariances (Cressie & Huang; Gneiting):